#### **Complex numbers** 1

$$\mathbb{C} = \{a + bi : a, b \in \mathbb{R}\}$$

Cartesian form: 
$$a + bi$$

Polar form:  $r \operatorname{cis} \theta$ 

## Operations

	Cartesian	Polar	z <sup></sup>	$^{1} = \frac{a - bi}{a^2 + b^2}$
$z_1 \pm z_2$	$(a \pm c)(b \pm d)i$	convert to $a + bi$		$\overline{z}$
$\frac{+k \times z}{-k \times z}$	$ka \pm kbi$	$kr \operatorname{cis} \theta$		$= \frac{1}{ z ^2}a$
$-k \times z$		$kr \operatorname{cis}(\theta \pm \pi)$		$= r \operatorname{cis}(-\theta)$
$z_1 \cdot z_2$	ac - bd + (ad + bc)i	$r_1 r_2 \operatorname{cis}(\theta_1 + \theta_2)$		
$z_1 \div z_2$	$(z_1\overline{z_2}) \div  z_2 ^2$	$\left(\frac{r_1}{r_2}\right) \operatorname{cis}(\theta_1 - \theta_2)$	Dividing over $\mathbb C$	

### Scalar multiplication in polar form

For  $k \in \mathbb{R}^+$ :

$$k\left(r\operatorname{cis}\theta\right) = kr\operatorname{cis}\theta$$

For  $k \in \mathbb{R}^-$ :

$$k(r \operatorname{cis} \theta) = kr \operatorname{cis} \left( \begin{cases} \theta - \pi & |0 < \operatorname{Arg}(z) \le \pi \\ \theta + \pi & |-\pi < \operatorname{Arg}(z) \le 0 \end{cases} \right)$$

## Conjugate

$$\overline{z} = a \mp bi$$
$$= r \operatorname{cis}(-\theta)$$

### On CAS: conjg(a+bi)

### Properties

$$\overline{z_1 \pm z_2} = \overline{z_1} \pm \overline{z_2}$$
$$\overline{z_1 \cdot z_2} = \overline{z_1} \cdot \overline{z_2}$$
$$\overline{kz} = k\overline{z} \quad | \quad k \in \mathbb{R}$$
$$z\overline{z} = (a + bi)(a - bi)$$
$$= a^2 + b^2$$
$$= |z|^2$$

## Modulus

$$|z| = |\vec{Oz}| = \sqrt{a^2 + b^2}$$

$$|z_1 z_2| = |z_1| |z_2|$$
$$\left| \frac{z_1}{z_2} \right| = \frac{|z_1|}{|z_2|}$$
$$|z_1 + z_2| \le |z_1| + |z_2|$$

## Multiplicative inverse

$z^{-1} = \frac{a - bi}{a^2 + b^2}$
$=rac{\overline{z}}{ z ^2}a$
$= r \operatorname{cis}(-\theta)$

$$\frac{z_1}{z_2} = z_1 z_2^{-1} = \frac{z_1 \overline{z_2}}{|z_2|^2} = \frac{(a+bi)(c-di)}{c^2 + d^2}$$

(rationalise denominator)

## Polar form

$$z = r \operatorname{cis} \theta$$
$$= r(\cos \theta + i \sin \theta)$$
$$\bullet \ r = |z| = \sqrt{\operatorname{Re}(z)^2 + \operatorname{Im}(z)^2}$$

- $\theta = \arg(z)$  On CAS: arg(a+bi)
- $\operatorname{Arg}(z) \in (-\pi, \pi)$  (principal argument)
- Convert on CAS:  $compToTrig(a+bi) \iff cExpand{r\cdot cisX}$
- Multiple representations:  $r \operatorname{cis} \theta = r \operatorname{cis}(\theta + 2n\pi)$  with  $n \in \mathbb{Z}$  revolutions

•  $\operatorname{cis} \pi = -1$ ,  $\cos 0 = 1$ 

## de Moivres' theorem

 $(r \operatorname{cis} \theta)^n = r^n \operatorname{cis}(n\theta)$  where  $n \in \mathbb{Z}$ 

## Complex polynomials

Include $\pm$ for all solutions, incl. imaginary		
Sum of squares	$z^{2} + a^{2} = z^{2} - (ai)^{2}$ = $(z + ai)(z - ai)$	
Sum of cubes	$a^3 \pm b^3 = (a \pm b)(a^2 \mp ab + b^2)$	
Division	P(z) = D(z)Q(z) + R(z)	
Remainder	Let $\alpha \in \mathbb{C}$ . Remainder of	
theorem	$P(z) \div (z - \alpha)$ is $P(\alpha)$	
Factor theorem	$z - \alpha$ is a factor of $P(z) \iff$	
	$P(\alpha) = 0 \text{ for } \alpha \in \mathbb{C}$	
Conjugate root	$P(z) = 0$ at $z = a \pm bi$ ( $\Longrightarrow$	
theorem	both $z_1$ and $\overline{z_1}$ are solutions)	

### nth roots

*n*th roots of  $z = r \operatorname{cis} \theta$  are:

$$z = r^{\frac{1}{n}} \operatorname{cis}\left(\frac{\theta + 2k\pi}{n}\right)$$

- Same modulus for all solutions
- Arguments separated by  $\frac{2\pi}{n}$  : there are *n* roots
- If one square root is a + bi, the other is -a bi
- Give one implicit *n*th root  $z_1$ , function is  $z = z_1^n$
- Solutions of  $z^n = a$  where  $a \in \mathbb{C}$  lie on the circle  $x^2 + y^2 = \left(|a|^{\frac{1}{n}}\right)^2$  (intervals of  $\frac{2\pi}{n}$ )

For  $0 = az^2 + bz + c$ , use quadratic formula:

$$z = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

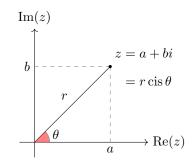
### Fundamental theorem of algebra

A polynomial of degree n can be factorised into n linear factors in  $\mathbb{C}$ :

$$\implies P(z) = a_n(z - \alpha_1)(z - \alpha_2)(z - \alpha_3)\dots(z - \alpha_n)$$

where 
$$\alpha_1, \alpha_2, \alpha_3, \ldots, \alpha_n \in \mathbb{C}$$

### Argand planes



- Multiplication by  $i \implies$  CCW rotation of  $\frac{\pi}{2}$
- Addition:  $z_1 + z_2 \equiv \overline{Oz_1} + \overline{Oz_2}$

### Sketching complex graphs

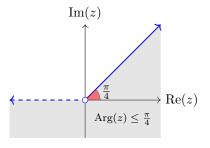
#### Linear

- $\operatorname{Re}(z) = c$  or  $\operatorname{Im}(z) = c$  (perpendicular bisector)
- $\operatorname{Im}(z) = m \operatorname{Re}(z)$
- $|z + a| = |z + b| \implies 2(a b)x = b^2 a^2$ Geometric: equidistant from a, b

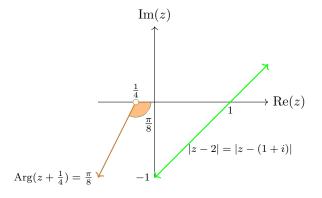
#### Circles

- $|z z_1|^2 = c^2 |z_2 + 2|^2$
- $|z (a + bi)| = c \implies (x a)^2 + (y b)^2 = c^2$

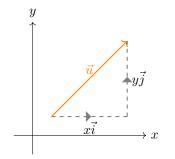
**Loci**  $\operatorname{Arg}(z) < \theta$ 



**Rays**  $\operatorname{Arg}(z-b) = \theta$ 



# 2 Vectors



## Column notation

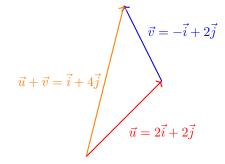
$$\begin{bmatrix} x \\ y \end{bmatrix} \iff x\mathbf{i} + y\mathbf{j}$$
$$\begin{bmatrix} x_2 - x_1 \\ y_2 - y_1 \end{bmatrix} \text{ between } A(x_1, y_1), \ B(x_2, y_2)$$

### Scalar multiplication

$$k \cdot (x\mathbf{i} + y\mathbf{j}) = kx\mathbf{i} + ky\mathbf{j}$$

For  $k \in \mathbb{R}^-$ , direction is reversed

### Vector addition



$$(x\boldsymbol{i}+y\boldsymbol{j})\pm(a\boldsymbol{i}+b\boldsymbol{j})=(x\pm a)\boldsymbol{i}+(y\pm b)\boldsymbol{j}$$

- Draw each vector head to tail then join lines
- Addition is commutative (parallelogram)

• 
$$\boldsymbol{u} - \boldsymbol{v} = \boldsymbol{u} + (-\boldsymbol{v}) \implies \overrightarrow{AB} = \boldsymbol{b} - \boldsymbol{a}$$

### Magnitude

$$|(x\boldsymbol{i}+y\boldsymbol{j})|=\sqrt{x^2+y^2}$$

## Parallel vectors

$$oldsymbol{u} || oldsymbol{v} \iff oldsymbol{u} = koldsymbol{v} ext{ where } k \in \mathbb{R} \setminus \{0\}$$

For parallel vectors  $\boldsymbol{a}$  and  $\boldsymbol{b}$ :

$$m{a} \cdot m{b} = egin{cases} |m{a}||m{b}| & ext{if same direction} \ -|m{a}||m{b}| & ext{if opposite directions} \end{cases}$$

### Perpendicular vectors

$$\boldsymbol{a} \perp \boldsymbol{b} \iff \boldsymbol{a} \cdot \boldsymbol{b} = 0$$
 (since  $\cos 90 = 0$ )

Unit vector 
$$|\hat{a}| = 1$$

$$\hat{oldsymbol{a}} = rac{1}{|oldsymbol{a}|}oldsymbol{a}$$
 $= oldsymbol{a} \cdot |oldsymbol{a}|$ 

Scalar product 
$$a \cdot b$$



$$\boldsymbol{a} \cdot \boldsymbol{b} = a_1 b_1 + a_2 b_2$$
$$= |\boldsymbol{a}| |\boldsymbol{b}| \cos \theta$$
$$(0 \le \theta \le \pi) \text{ - from cosine rule}$$

On CAS: dotP([a b c], [d e f])

### Properties

1. 
$$k(\boldsymbol{a} \cdot \boldsymbol{b}) = (k\boldsymbol{a}) \cdot \boldsymbol{b} = \boldsymbol{a} \cdot (k\boldsymbol{b})$$
  
2.  $\boldsymbol{a} \cdot \boldsymbol{0} = 0$   
3.  $\boldsymbol{a} \cdot (\boldsymbol{b} + \boldsymbol{c}) = \boldsymbol{a} \cdot \boldsymbol{b} + \boldsymbol{a} \cdot \boldsymbol{c}$   
4.  $\boldsymbol{i} \cdot \boldsymbol{i} = \boldsymbol{j} \cdot \boldsymbol{j} = \boldsymbol{k} \cdot \boldsymbol{k} = 1$   
5.  $\boldsymbol{a} \cdot \boldsymbol{b} = 0 \implies \boldsymbol{a} \perp \boldsymbol{b}$   
6.  $\boldsymbol{a} \cdot \boldsymbol{a} = |\boldsymbol{a}|^2 = a^2$ 

### Angle between vectors

 $\cos \theta = \frac{\boldsymbol{a} \cdot \boldsymbol{b}}{|\boldsymbol{a}||\boldsymbol{b}|} = \frac{a_1 b_1 + a_2 b_2}{|\boldsymbol{a}||\boldsymbol{b}|}$ On CAS: angle([a b c], [a b c]) (Action  $\rightarrow$  Vector  $\rightarrow$ Angle)

## Angle between vector and axis

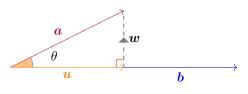
For  $a = a_1 i + a_2 j + a_3 k$  which makes angles  $\alpha, \beta, \gamma$  with positive side of x, y, z axes:

$$\cos \alpha = \frac{a_1}{|\mathbf{a}|}, \quad \cos \beta = \frac{a_2}{|\mathbf{a}|}, \quad \cos \gamma = \frac{a_3}{|\mathbf{a}|}$$

On CAS: angle([a b c], [1 0 0])

for angle between  $a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$  and x-axis

# Projections & resolutes



### $\parallel b$ (vector projection/resolute)

$$egin{aligned} m{u} &= rac{m{a} \cdot m{b}}{|m{b}|^2}m{b} \ &= \left(rac{m{a} \cdot m{b}}{|m{b}|}
ight) \left(rac{m{b}}{|m{b}|}
ight) \ &= (m{a} \cdot \hat{m{b}})\hat{m{b}} \end{aligned}$$

### $\perp b$ (perpendicular projection)

$$w = a - u$$

|u| (scalar projection/resolute)

$$s = |\boldsymbol{u}|$$
$$= \boldsymbol{a} \cdot \hat{\boldsymbol{b}}$$
$$= \frac{\boldsymbol{a} \cdot \boldsymbol{b}}{|\boldsymbol{b}|}$$
$$= |\boldsymbol{a}| \cos \theta$$

Rectangular ( $\parallel, \perp$ ) components

$$a=rac{oldsymbol{a}\cdotoldsymbol{b}}{oldsymbol{b}\cdotoldsymbol{b}}b+\left(oldsymbol{a}-rac{oldsymbol{a}\cdotoldsymbol{b}}{oldsymbol{b}\cdotoldsymbol{b}}b
ight)$$

## Vector proofs

**Concurrent:** intersection of  $\geq 3$  lines

## Collinear points

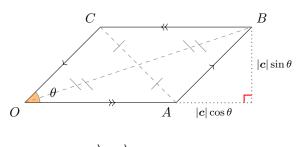
$$\geq$$
 3 points lie on the same line

e.g. Prove that  

$$\overrightarrow{AC} = m\overrightarrow{AB} \iff c = (1-m)a + mb$$
  
 $\implies c = \overrightarrow{OA} + \overrightarrow{AC}$   
 $= \overrightarrow{OA} + m\overrightarrow{AB}$   
 $= a + m(b - a)$   
 $= a + mb - ma$   
 $= (1 - m)a + mb$ 

Also, 
$$\implies \overrightarrow{OC} = \lambda \overrightarrow{OA} + \mu \overrightarrow{OB}$$
  
where  $\lambda + \mu = 1$   
If C lies along  $\overrightarrow{AB}$ ,  $\implies 0 < \mu < 1$ 

### Parallelograms



- Diagonals  $\overrightarrow{OB}$ ,  $\overrightarrow{AC}$  bisect each other
- If diagonals are equal length, it is a rectangle

• 
$$|\overrightarrow{OB}|^2 + |\overrightarrow{CA}|^2 = |\overrightarrow{OA}|^2 + |\overrightarrow{AB}|^2 + |\overrightarrow{CB}|^2 + |\overrightarrow{OC}|^2$$

• Area =  $\boldsymbol{c} \cdot \boldsymbol{a}$ 

### Useful vector properties

- $\boldsymbol{a} \parallel \boldsymbol{b} \implies \boldsymbol{b} = k\boldsymbol{a}$  for some  $k \in \mathbb{R} \setminus \{0\}$
- If *a* and *b* are parallel with at least one point in common, then they lie on the same straight line
- $\boldsymbol{a} \perp \boldsymbol{b} \iff \boldsymbol{a} \cdot \boldsymbol{b} = 0$
- $\boldsymbol{a} \cdot \boldsymbol{a} = |\boldsymbol{a}|^2$

### Linear dependence

 $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$  are linearly dependent if they are  $\nexists$  and:

$$0 = k\boldsymbol{a} + l\boldsymbol{b} + m\boldsymbol{c}$$
  
$$\therefore \boldsymbol{c} = m\boldsymbol{a} + n\boldsymbol{b} \quad \text{(simultaneous)}$$

*a*, *b*, and *c* are linearly independent if no vector in the set is expressible as a linear combination of other vectors in set, or if they are parallel.

### Three-dimensional vectors

Right-hand rule for axes: z is up or out of page.

Parametric vectors

x

Parametric equation of line through point  $(x_0, y_0, z_0)$ and parallel to  $a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$  is:

(1, 1, 1)

y

$$\begin{cases} x = x_o + a \cdot t \\ y = y_0 + b \cdot t \\ z = z_0 + c \cdot t \end{cases}$$

# **3** Circular functions

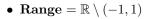
 $\sin(bx) \text{ or } \cos(bx): \text{ period} = \frac{2\pi}{b}$  $\tan(nx): \text{ period} = \frac{\pi}{n}$ asymptotes at  $x = \frac{(2k+1)\pi}{2n} \mid k \in \mathbb{Z}$ 

### **Reciprocal functions**

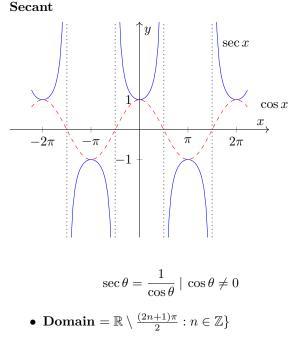
### Cosecant

$$\operatorname{cosec} \theta = \frac{1}{\sin \theta} \mid \sin \theta \neq 0$$

• **Domain** =  $\mathbb{R} \setminus n\pi : n \in \mathbb{Z}$ 

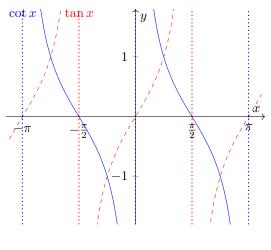


- Turning points at  $\theta = \frac{(2n+1)\pi}{2} \mid n \in \mathbb{Z}$
- Asymptotes at  $\theta = n\pi \mid n \in \mathbb{Z}$



- Range =  $\mathbb{R} \setminus (-1, 1)$
- Turning points at  $\theta = n\pi \mid n \in \mathbb{Z}$
- Asymptotes at  $\theta = \frac{(2n+1)\pi}{2} \mid n \in \mathbb{Z}$

### Cotangent



$$\cot \theta = \frac{\cos \theta}{\sin \theta} \mid \sin \theta \neq 0$$

- **Domain** =  $\mathbb{R} \setminus \{n\pi : n \in \mathbb{Z}\}$
- Range =  $\mathbb{R}$
- Asymptotes at  $\theta = n\pi \mid n \in \mathbb{Z}$

#### Symmetry properties

$$\sec(\pi \pm x) = -\sec x$$
$$\sec(-x) = \sec x$$
$$\cose(-x) = \pm \csc x$$
$$\csc(\pi \pm x) = \pm \csc x$$
$$\cot(\pi \pm x) = \pm \cot x$$
$$\cot(\pi \pm x) = \pm \cot x$$
$$\cot(-x) = -\cot x$$

#### Complementary properties

$$\sec\left(\frac{\pi}{2} - x\right) = \operatorname{cosec} x$$
$$\operatorname{cosec}\left(\frac{\pi}{2} - x\right) = \sec x$$
$$\operatorname{cot}\left(\frac{\pi}{2} - x\right) = \tan x$$
$$\tan\left(\frac{\pi}{2} - x\right) = \cot x$$

#### Pythagorean identities

 $1 + \cot^2 x = \csc^2 x$ , where  $\sin x \neq 0$  $1 + \tan^2 x = \sec^2 x$ , where  $\cos x \neq 0$ 

## Compound angle formulas

$$\cos(x \pm y) = \cos x + \cos y \mp \sin x \sin y$$

 $\sin(x \pm y) = \sin x \cos y \pm \cos x \sin y$ 

$$\tan(x \pm y) = \frac{\tan x \pm \tan y}{1 \mp \tan x \tan y}$$

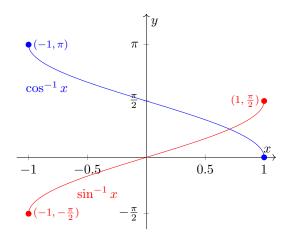
## Double angle formulas

 $\cos 2x = \cos^2 x - \sin^2 x$  $= 1 - 2\sin^2 x$  $= 2\cos^2 x - 1$ 

 $\sin 2x = 2\sin x \cos x$ 

 $\tan 2x = \frac{2\tan x}{1 - \tan^2 x}$ 

## Inverse circular functions



Inverse functions:  $f(f^{-1}(x)) = x$  (restrict domain)

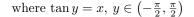
$$\sin^{-1}: [-1,1] \to \mathbb{R}, \quad \sin^{-1}x = y$$

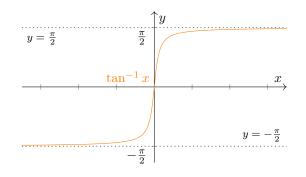
where 
$$\sin y = x, y \in \left[\frac{-\pi}{2}, \frac{\pi}{2}\right]$$

$$\cos^{-1}: [-1,1] \to \mathbb{R}, \quad \cos^{-1}x = y$$

where 
$$\cos y = x, y \in [0, \pi]$$

 $\tan^{-1}: \mathbb{R} \to \mathbb{R}, \quad \tan^{-1} x = y$ 





# 4 Differential calculus

### Limits

$$\lim_{x \to a} f(x)$$

 $L^-, L^+$  limit from below/above lim<sub>x \to a</sub> f(x) limit of a point

For solving  $x \to \infty$ , put all x terms in denominators e.g.

$$\lim_{x \to \infty} \frac{2x+3}{x-2} = \frac{2+\frac{3}{x}}{1-\frac{2}{x}} = \frac{2}{1} = 2$$

#### Limit theorems

- 1. For constant function f(x) = k,  $\lim_{x \to a} f(x) = k$
- 2.  $\lim_{x \to a} (f(x) \pm g(x)) = F \pm G$
- 3.  $\lim_{x \to a} (f(x) \times g(x)) = F \times G$
- 4. :  $\lim_{x \to a} c \times f(x) = cF$  where c = constant
- 5.  $\lim_{x \to a} \frac{f(x)}{g(x)} = \frac{F}{G}, G \neq 0$
- 6. f(x) is continuous  $\iff L^- = L^+ = f(x) \ \forall x$

#### Gradients of secants and tangents

Secant (chord) - line joining two points on curve Tangent - line that intersects curve at one point

### First principles derivative

$$f'(x) = \lim_{\delta x \to 0} \frac{\delta y}{\delta x} = \frac{dy}{dx}$$

#### Logarithmic identities

 $\log_b(xy) = \log_b x + \log_b y$  $\log_b x^n = n \log_b x$  $\log_b y^{x^n} = x^n \log_b y$ 

#### Index identities

 $b^{m+n} = b^m \cdot b^n$  $(b^m)^n = b^{m \cdot n}$  $(b \cdot c)^n = b^n \cdot c^n$  $a^m \div a^n = a^{m-n}$ 

### **Reciprocal derivatives**

$$\frac{1}{\frac{dy}{dx}} = \frac{dx}{dy}$$

Differentiating x = f(y)

Find 
$$\frac{dx}{dy}$$
, then  $\frac{dy}{dx} = \frac{1}{\left(\frac{dx}{dy}\right)}$ 

-

Second derivative

$$f(x) \longrightarrow f'(x) \longrightarrow f''(x)$$
$$\implies y \longrightarrow \frac{dy}{dx} \longrightarrow \frac{d^2y}{dx^2}$$

Order of polynomial nth derivative decrements each time the derivative is taken

#### **Points of Inflection**

Stationary point - i.e. f'(x) = 0Point of inflection - max |gradient| (i.e. f'' = 0)

- if f'(a) = 0 and f''(a) > 0, then point (a, f(a)) is a local min (curve is concave up)
- if f'(a) = 0 and f''(a) < 0, then point (a, f(a)) is local max (curve is concave down)
- if f''(a) = 0, then point (a, f(a)) is a point of inflection
- if also f'(a) = 0, then it is a stationary point of inflection

### Implicit Differentiation

Used for differentiating circles etc.

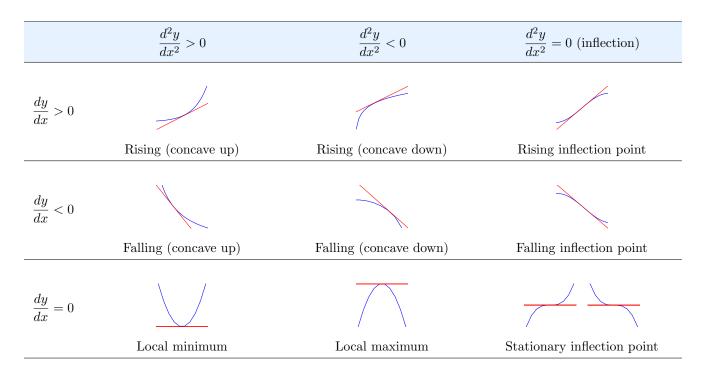
If p and q are expressions in x and y such that p = q, for all x and y, then:

$$\frac{dp}{dx} = \frac{dq}{dx}$$
 and  $\frac{dp}{dy} = \frac{dq}{dy}$ 

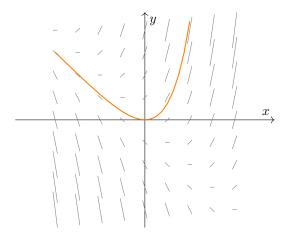
On CAS

Action  $\rightarrow$  Calculation

impDiff( $y^2$ +ax=5, x, y) (returns y' = ...)







## Parametric equations

For each point on (f(t), g(t)):

$$\frac{dy}{dt} = \frac{dy}{dx} \cdot \frac{dx}{dt}$$
$$\therefore \frac{dy}{dx} = \frac{\left(\frac{dy}{dt}\right)}{\left(\frac{dx}{dt}\right)} \text{ provided } \frac{dx}{dt} \neq 0$$

Also...

$$\frac{d^2y}{dx^2} = \frac{\left(\frac{dy'}{dt}\right)}{\left(\frac{dx}{dt}\right)} \text{ where } y' = \frac{dy}{dx}$$

### Integration

$$\int f(x) \cdot dx = F(x) + c \quad \text{where } F'(x) = f(x)$$

Definite integrals

$$\int_{a}^{b} f(x) \cdot dx = [F(x)]_{a}^{b} = F(b) - F(a)$$

• Signed area enclosed by

$$y = f(x), \quad y = 0, \quad x = a, \quad x = b.$$

• Integrand is f.

## Properties

$$\int_{a}^{b} f(x) dx = \int_{a}^{c} f(x) dx + \int_{c}^{b} f(x) dx$$
$$\int_{a}^{a} f(x) dx = 0$$
$$\int_{a}^{b} k \cdot f(x) dx = k \int_{a}^{b} f(x) dx$$
$$\int_{a}^{b} f(x) \pm g(x) dx = \int_{a}^{b} f(x) dx \pm \int_{a}^{b} g(x) dx$$
$$\int_{a}^{b} f(x) dx = -\int_{b}^{a} f(x) dx$$

Integration by substitution

$$\int f(u)\frac{du}{dx} \cdot dx = \int f(u) \cdot du$$

f(u) must be 1:1  $\implies$  one x for each y

e.g. for 
$$y = \int (2x+1)\sqrt{x+4} \cdot dx$$
  
let  $u = x+4$   
 $\implies \frac{du}{dx} = 1$   
 $\implies x = u-4$   
then  $y = \int (2(u-4)+1)u^{\frac{1}{2}} \cdot du$   
(column on permut integral)

(solve as normal integral)

#### Definite integrals by substitution

For  $\int_a^b f(x) \frac{du}{dx} \cdot dx$ , evaluate new *a* and *b* for  $f(u) \cdot du$ .

#### **Trigonometric integration**

$$\sin^m x \cos^n x \cdot dx$$

*m* is odd: m = 2k + 1 where  $k \in \mathbb{Z}$   $\implies \sin^{2k+1} x = (\sin^2 z)^k \sin x = (1 - \cos^2 x)^k \sin x$ Substitute  $u = \cos x$ 

*n* is odd: n = 2k + 1 where  $k \in \mathbb{Z}$   $\implies \cos^{2k+1} x = (\cos^2 x)^k \cos x = (1 - \sin^2 x)^k \cos x$ Substitute  $u = \sin x$ 

m and n are even: use identities...

- $\sin^2 x = \frac{1}{2}(1 \cos 2x)$
- $\cos^2 x = \frac{1}{2}(1 + \cos 2x)$
- $\sin 2x = 2\sin x \cos x$

### Partial fractions

To factorise  $f(x) = \frac{\delta}{\alpha \cdot \beta}$ :

$$\frac{\delta}{\alpha \cdot \beta \cdot \gamma} = \frac{A}{\alpha} + \frac{B}{\beta} + \frac{C}{\gamma} \tag{1}$$

Multiply by  $(\alpha \cdot \beta \cdot \gamma)$ :

$$\delta = \beta \gamma A + \alpha \gamma B + \alpha \beta C \tag{2}$$

Substitute  $x = \{\alpha, \beta, \gamma\}$  into (2) to find denominators

#### **Repeated linear factors**

$$\frac{p(x)}{(x-a)^n} = \frac{A_1}{(x-a)} + \frac{A_2}{(x-a)^2} + \dots + \frac{A_n}{(x-a)^n}$$

#### Irreducible quadratic factors

e.g. 
$$\frac{3x-4}{(2x-3)(x^2+5)} = \frac{A}{2x-3} + \frac{Bx+C}{x^2+5}$$

On CAS

Action  $\rightarrow$  Transformation: expand(..., x) To reverse, use combine(...)

### Graphing integrals on CAS

On CAS

```
In main: Interactive \rightarrow Calculation \rightarrow \int
Restrictions: Define f(x)=.. then f(x)|x>..
```

### Applications of antidifferentiation

- x-intercepts of y = f(x) identify x-coordinates of stationary points on y = F(x)
- nature of stationary points is determined by sign of y = f(x) on either side of its x-intercepts
- if f(x) is a polynomial of degree n, then F(x) has degree n + 1

To find stationary points of a function, substitute x value of given point into derivative. Solve for  $\frac{dy}{dx} = 0$ . Integrate to find original function.

### Solids of revolution

Approximate as sum of infinitesimally-thick cylinders

#### Rotation about *x*-axis

$$V = \pi \int_{x=a}^{x=b} f(x)^2 \, dx$$

Rotation about *y*-axis

$$V = \pi \int_{y=a}^{y=b} x^2 \, dy$$
$$= \pi \int_{y=a}^{y=b} (f(y))^2 \, dy$$

Regions not bound by y = 0

V =

$$\pi \int_{a}^{b} f(x)^{2} - g(x)^{2} dx$$
  
where  $f(x) > g(x)$ 

#### Length of a curve

$$L = \int_{a}^{b} \sqrt{1 + (\frac{dy}{dx})^2} \, dx \quad \text{(Cartesian)}$$

$$L = \int_{a}^{b} \sqrt{\frac{dx}{dt} + (\frac{dy}{dt})^{2}} dt \quad \text{(parametric)}$$

On CAS

- a) Evaluate formula
- b) Interactive  $\rightarrow$  Calculation  $\rightarrow$  Line  $\rightarrow$  arcLen

#### Rates

Gradient at a point on parametric curve

$$\frac{dy}{dx} = \frac{dy}{dt} \div \frac{dx}{dt} \mid \frac{dx}{dt} \neq 0 \text{ (chain rule)}$$

$$\frac{d^2}{dx^2} = \frac{d(y')}{dx} = \frac{dy'}{dt} \div \frac{dx}{dt} \mid y' = \frac{dy}{dx}$$

### **Rational functions**

$$f(x) = \frac{P(x)}{Q(x)}$$
 where  $P, Q$  are polynomial functions

#### Addition of ordinates

- when two graphs have the same ordinate, *y*-coordinate is double the ordinate
- when two graphs have opposite ordinates, *y*-coordinate is 0 i.e. (*x*-intercept)
- when one of the ordinates is 0, the resulting ordinate is equal to the other ordinate

### Fundamental theorem of calculus

If f is continuous on [a, b], then

$$\int_{a}^{b} f(x) dx = F(b) - F(a)$$
  
where  $F = \int f dx$ 

### **Differential** equations

**Order** - highest power inside derivative

**Degree** - highest power of highest derivative e.g.  $\left(\frac{dy^2}{d^2}x\right)^3$  order 2, degree 3

#### Verifying solutions

Start with  $y = \ldots$ , and differentiate. Substitute into original equation.

#### Function of the dependent variable

If  $\frac{dy}{dx} = g(y)$ , then  $\frac{dx}{dy} = 1 \div \frac{dy}{dx} = \frac{1}{g(y)}$ . Integrate both sides to solve equation. Only add c on one side. Express  $e^c$  as A.

#### Mixing problems

$$\left(\frac{dm}{dt}\right)_{\Sigma} = \left(\frac{dm}{dt}\right)_{\rm in} - \left(\frac{dm}{dt}_{\rm out}\right)$$

Separation of variables

If 
$$\frac{dy}{dx} = f(x)g(y)$$
, then:

$$\int f(x) \, dx = \int \frac{1}{g(y)} \, dy$$

#### Euler's method for solving DEs

$$\frac{f(x+h) - f(x)}{h} \approx f'(x) \quad \text{for small } h$$

$$\implies f(x+h) \approx f(x) + hf'(x)$$

Derivatives			Antiderivativ	ves	
f(x)	f'(x)		f(x)	$\int f(x) \cdot dx$	
$\sin x$	$\cos x$		k (constant)	kx + c	
$\sin ax$	$a\cos ax$		$x^n$	$\frac{1}{n+1}x^{n+1}$	
$\cos x$	$-\sin x$		$ax^{-n}$	$a \cdot \log_e  x  + c$	
$\cos ax$	$-a\sin ax$		$\frac{1}{ax+b}$	$\frac{1}{a}\log_e(ax+b) + c$	
an f(x)	$f^2(x)\sec^2 f(x)$		$(ax+b)^n$	$\frac{1}{a(n+1)}(ax+b)^{n-1}$	$1 + c \mid n \neq 1$
$e^x$	$e^x$		$(ax+b)^{-1}$	$\frac{1}{a}\log_e ax+b +c$	
$e^{ax}$	$ae^{ax}$		$e^{kx}$	$\frac{1}{k}e^{kx} + c$	
$ax^{nx}$	$an \cdot e^{nx}$		$e^k$	$e^k x + c$	
$\log_e x$	$\frac{1}{x}$		$\sin kx$	$\frac{-1}{k}\cos(kx) + c$	
$\log_e ax$	$\frac{1}{x}$		$\cos kx$	$\frac{1}{k}\sin(kx) + c$	
$\log_e f(x)$	$\frac{f'(x)}{f(x)}$		$\sec^2 kx$	$\frac{1}{k}\tan(kx) + c$	
$\sin(f(x))$	$f'(x) \cdot \cos(f(x))$		$\frac{1}{\sqrt{a^2 - x^2}}$	$\sin^{-1}\frac{x}{a} + c \mid a > 0$	
$\sin^{-1}x$	$\frac{1}{\sqrt{1-x^2}}$			$\cos^{-1}\frac{x}{a} + c \mid a > 0$	
	$\frac{-1}{\sqrt{1-x^2}}$		$\frac{a}{a^2-x^2}$	$\tan^{-1}\frac{x}{a} + c$	
$\tan^{-1} x$	$\frac{1}{1+x^2}$		$rac{f'(x)}{f(x)}$	$\log_e f(x) + c$	
$rac{d}{dy}f(y)$		(reciprocal)	$\int f(u) \cdot \frac{du}{dx} \cdot dx$	$\int f(u) \cdot du$	(substitution)
uv	$u\frac{dv}{dx} + v\frac{du}{dx}$	(product rule)	$f(x) \cdot g(x)$	$\int [f'(x) \cdot g(x)] dx + \int$	$\int [g'(x)f(x)]dx$
$\frac{u}{v}$	$\frac{v\frac{du}{dx} - u\frac{dv}{dx}}{v^2}$	(quotient rule)	Note $\sin^{-1}\left(\frac{x}{a}\right) +$	$-\cos^{-1}\left(\frac{x}{a}\right)$ is constant	$nt \ \forall \ x \in (-a, a)$
f(g(x))	$f'(g(x)) \cdot g'(x)$				

### 11

# 5 Kinematics & Mechanics

### **Constant** acceleration

- **Position** relative to origin
- Displacement relative to starting point

#### Velocity-time graphs

- Displacement: signed area between graph and t axis
- Distance travelled: *total* area between graph and *t* axis

$$acceleration = \frac{d^2x}{dt^2} = \frac{dv}{dt} = v\frac{dv}{dx} = \frac{d}{dx}\left(\frac{1}{2}v^2\right)$$

$$\boxed{\begin{array}{c} & \text{no} \\ \hline & v = u + at & x \\ v^2 = u^2 + 2as & t \\ s = \frac{1}{2}(v+u)t & a \\ s = ut + \frac{1}{2}at^2 & v \\ \hline & s = vt - \frac{1}{2}at^2 & u \\ \hline & v_{\text{avg}} = \frac{\Delta \text{position}}{\Delta t}$$

$$speed = |\text{velocity}| \\ = \sqrt{v_x^2 + v_y^2 + v_z^2}$$

Distance travelled between  $t = a \rightarrow t = b$ :

$$= \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} \cdot dt$$

Shortest distance between  $r(t_0)$  and  $r(t_1)$ :

$$= |\boldsymbol{r}(t_1) - \boldsymbol{r}(t_2)|$$

Vector functions

$$\boldsymbol{r}(t) = x\boldsymbol{i} + y\boldsymbol{j} + z\boldsymbol{k}$$

- If r(t) ≡ position with time, then the graph of endpoints of r(t) ≡ Cartesian path
- Domain of r(t) is the range of x(t)
- Range of r(t) is the range of y(t)

### Vector calculus

### Derivative

Let  $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)(\mathbf{j})$ . If both x(t) and y(t) are differentiable, then:

$$\boldsymbol{r}(t) = \boldsymbol{x}(t)\boldsymbol{i} + \boldsymbol{y}(t)\boldsymbol{j}$$

# 6 Dynamics

## **Resolution of forces**

 $\ensuremath{\textbf{Resultant}}$  force is sum of force vectors

#### In angle-magnitude form

Cosine rule: 
$$c^2 = a^2 + b^2 - 2ab\cos\theta$$
  
Sine rule:  $\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}$ 

### In i - j form

Vector of  $a \, \text{N}$  at  $\theta$  to x axis is equal to  $a \cos \theta \mathbf{i} + a \sin \theta \mathbf{j}$ . Convert all force vectors then add.

To find angle of an ai + bj vector, use  $\theta = \tan^{-1} \frac{b}{a}$ 

#### Resolving in a given direction

The resolved part of a force P at angle  $\theta$  is has magnitude  $P\cos\theta$ 

To convert force  $||\vec{OA}|$  to angle-magnitude form, find component  $\perp \vec{OA}$  then:

$$|\mathbf{r}| = \sqrt{\left(||\vec{OA}\rangle^2 + \left(\perp \vec{OA}\right)^2\right)}$$
$$\theta = \tan^{-1} \frac{\perp \vec{OA}}{||\vec{OA}|}$$

### Newton's laws

1. Velocity is constant without  $\Sigma F$ 

2.  $\frac{d}{dt}\rho \propto \Sigma F \implies \mathbf{F} = m\mathbf{a}$ 

3. Equal and opposite forces

#### Weight

A mass of m kg has force of mg acting on it

#### Momentum $\rho$

 $\rho = mv$  (units kg m/s or Ns)

#### Reaction force ${\it R}$

- With no vertical velocity, R = mg
- With vertical acceleration, |R| = m|a| mg
- With force F at angle  $\theta$ , then  $R = mg F \sin \theta$

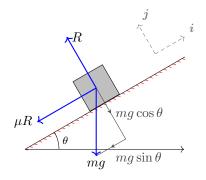
#### Friction

 $F_R = \mu R$  (friction coefficient)

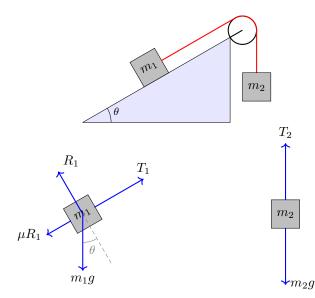
#### Inclined planes

$$m{F} = |m{F}| \cos heta m{i} + |m{F}| \sin heta m{j}$$

- Normal force R is at right angles to plane
- Let direction up the plane be *i* and perpendicular to plane *j*



### Connected particles



• **Suspended pulley:** tension in both sections of rope are equal

 $|a| = g \frac{m_1 - m_2}{m_1 + m_2}$  where  $m_1$  accelerates down With tension:

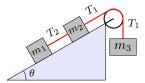
$$\begin{cases} m_1g - T = m_1a \\ T - m_2g = m_2a \end{cases} \implies m_1g - m_2g = m_1a + m_2a$$

• String pulling mass on inclined pane: Resolve parallel to plane

$$T - mg\sin\theta = ma$$

- Linear connection: find acceleration of system first
- Pulley on right angle:  $a = \frac{m_2 g}{m_1 + m_2}$  where  $m_2$  is suspended (frictionless on both surfaces)
- Pulley on edge of incline: find downwards force W<sub>2</sub> and components of mass on plane

In this example, note  $T_1 \neq T_2$ :



### Equilibrium

$$\frac{A}{\sin a} = \frac{B}{\sin b} = \frac{C}{\sin c} \qquad \text{(Lami's theorem)}$$
$$c^2 = a^2 + b^2 - 2ab\cos\theta \qquad \text{(cosine rule)}$$

Three methods:

- 1. Lami's theorem (sine rule)
- 2. Triangle of forces (cosine rule)
- 3. Resolution of forces ( $\Sigma F = 0$  simultaneous)

### On CAS

**To verify:** Geometry tab, then select points with normal cursor. Click right arrow at end of toolbar and input point, then lock known constants.

#### Variable forces (DEs)

$$a = \frac{d^2x}{dt^2} = \frac{dv}{dt} = v\frac{dv}{dx} = \frac{d}{dx}\left(\frac{1}{2}v^2\right)$$

# 7 Statistics

### Continuous random variables

A continuous random variable X has a pdf f such that:

1. 
$$f(x) \ge 0 \forall x$$

2.  $\int_{-\infty}^{\infty} f(x) \, dx = 1$ 

$$E(X) = \int_{\mathbf{X}} (x \cdot f(x)) \, dx$$
$$\operatorname{Var}(X) = E\left[ (X - \mu)^2 \right]$$

$$\Pr(X \le c) = \int_{-\infty}^{c} f(x) \, dx$$

#### Two random variables X, Y

If X and Y are independent:

$$E(aX + bY) = a E(X) + b E(Y)$$
$$Var(aX \pm bY \pm c) = a^{2} Var(X) + b^{2} Var(Y)$$

Linear functions  $X \to aX + b$ 

$$\Pr(Y \le y) = \Pr(aX + b \le y)$$
$$= \Pr\left(X \le \frac{y - b}{a}\right)$$
$$= \int_{-\infty}^{\frac{y - b}{a}} f(x) \, dx$$

Mean: E(aX + b) = a E(X) + bVariance:  $Var(aX + b) = a^2 Var(X)$ 

$$E(X^{2}) = \operatorname{Var}(X) - [E(X)]^{2}$$
$$E(X^{n}) = \Sigma x^{n} \cdot p(x) \qquad \text{(non-linear)}$$
$$\neq [E(X)]^{n}$$

$$E(aX \pm b) = aE(X) \pm b$$
 (linear)

$$E(b) = b \qquad (\forall b \in \mathbb{R})$$

E(X + Y) = E(X) + E(Y) (two variables)

### Sample mean

Approximation of the **population mean** determined experimentally.

$$\overline{x} = \frac{\Sigma x}{n}$$

where

n is the size of the sample (number of sample points) x is the value of a sample point

- 1. Spreadsheet
- 2. In cell A1:

mean(randNorm(sd, mean, sample size))

- 3. Edit  $\rightarrow$  Fill  $\rightarrow$  Fill Range
- 4. Input range as A1:An where *n* is the number of samples
- 5. Graph  $\rightarrow$  Histogram

Sample size of n

$$\overline{X} = \sum_{i=1}^{n} \frac{x_i}{n} = \frac{\sum x}{n}$$

Sample mean is distributed with mean  $\mu$  and sd  $\frac{\sigma}{\sqrt{n}}$  (approaches these values for increasing sample size n). For a new distribution with mean of n trials, E(X') = E(X),  $sd(X') = \frac{sd(X)}{\sqrt{n}}$ 

### Expectation theorems

For some non-linear function g, the expected value E(g(X)) is not equal to g(E(X)).

#### On CAS

- Spreadsheet → Catalog → randNorm(sd, mean, n) where n is the number of samples. Show histogram with Histogram key in top left
- To calculate parameters of a dataset: Calc  $\rightarrow$  One-variable

#### Normal distributions

$$Z = \frac{X - \mu}{\sigma}$$

Normal distributions must have area (total prob.) of 1

```
\implies \int_{-\infty}^{\infty} f(x) \, dx = 1
```

mean = mode = median

Always express z as +ve. Express confidence interval as ordered pair.

#### Central limit theorem

If X is randomly distributed with mean  $\mu$  and sd  $\sigma$ , then with an adequate sample size n the distribution of the sample mean  $\overline{X}$  is approximately normal with mean  $E(\overline{X})$  and  $\operatorname{sd}(\overline{X}) = \frac{\sigma}{\sqrt{n}}$ .

#### **Confidence** intervals

- Point estimate: single-valued estimate of the population mean from the value of the sample mean  $\overline{x}$
- Interval estimate: confidence interval for population mean  $\mu$
- C% confidence interval  $\implies C\%$  of samples will contain population mean  $\mu$

#### 95% confidence interval

For 95% c.i. of population mean  $\mu :$ 

$$x \in \left(\overline{x} \pm 1.96 \frac{\sigma}{\sqrt{n}}\right)$$

where:

 $\overline{x}$  is the sample mean

```
\sigma is the population sd
```

n is the sample size from which  $\overline{x}$  was calculated

On CAS

 $\begin{aligned} \text{Menu} &\to \text{Stats} \to \text{Calc} \to \text{Interval} \\ \text{Set } Type = One\text{-}Sample \ Z \ Int \\ \text{and select } Variable \end{aligned}$ 

### Margin of error

For 95% confidence interval of  $\mu$ :

$$M = 1.96 \times \frac{\sigma}{\sqrt{n}}$$
$$\implies n = \left(\frac{1.96\sigma}{M}\right)^2$$

Always round n up to a whole number of samples.

### General case

For C% c.i. of population mean  $\mu$ :

$$x \in \left(\overline{x} \pm k \frac{\sigma}{\sqrt{n}}\right)$$

where k is such that  $Pr(-k < Z < k) = \frac{C}{100}$ 

#### Confidence interval for multiple trials

For a set of n confidence intervals (samples), there is  $0.95^n$  chance that all n intervals contain the population mean  $\mu$ .

# 8 Hypothesis testing

Note hypotheses are always expressed in terms of population parameters

#### Null hypothesis H<sub>0</sub>

Sample drawn from population has same mean as control population, and any difference can be explained by sample variations.

### Alternative hypothesis $H_1$

Amount of variation from control is significant, despite standard sample variations.

## p-value

Probability of observing a value of the sample statistic as significant as the one observed, assuming null hypothesis is true.

For one-tail tests:

$$p\text{-value} = \Pr\left(\overline{X} \leq \mu(\mathbf{H}_1) \mid \mu = \mu(\mathbf{H}_0)\right)$$
$$= \Pr\left(Z \leq \frac{(\mu(\mathbf{H}_1) - \mu(\mathbf{H}_0)) \cdot \sqrt{n}}{\operatorname{sd}(X)}\right)$$

then use normCdf with std. norm.

p	Conclusion
> 0.05	insufficient evidence against $\mathbf{H}_0$
$< 0.05 \ (5\%)$	good evidence against $\mathbf{H}_0$
< 0.01 (1%)	strong evidence against $\mathbf{H}_0$
$< 0.001 \ (0.1\%)$	very strong evidence against $\mathbf{H}_0$

### Significance level $\alpha$

The condition for rejecting the null hypothesis.

If  $p < \alpha$ , null hypothesis is **rejected** 

If  $p > \alpha$ , null hypothesis is **accepted** 

#### z-test

Hypothesis test for a mean of a sample drawn from a normally distributed population with a known standard deviation.

### On CAS

Menu $\rightarrow$ Statistics $\rightarrow$ Calc $\rightarrow$ Test.		
Select One-Sample Z-Test and Variable, then in-		
put:		
$\mu$ cond:	same operator as $\mathbf{H}_1$	
$\mu_0$ :	expected sample mean (null hypoth-	
	esis)	
$\sigma$ :	standard deviation (null hypothesis)	
$\overline{x}$ :	sample mean	
n:	sample size	

## One-tail and two-tail tests

p-value (two-tail) =  $2 \times p$ -value (one-tail)

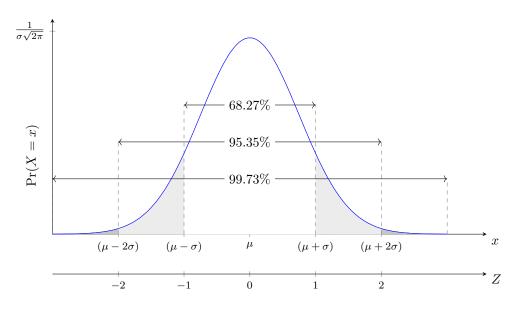
#### One tail

- $\mu$  has changed in one direction
- State " $\mathbf{H}_1 : \mu \leq$ known population mean"

#### Two tail

- Direction of  $\Delta \mu$  is ambiguous
- State " $\mathbf{H}_1 : \mu \neq \text{known population mean}$ "

$$p\text{-value} = \Pr(|\overline{X} - \mu| \ge |\overline{x}_0 - \mu|)$$
$$= \left(|Z| \ge \left|\frac{\overline{x}_0 - \mu}{\sigma \div \sqrt{n}}\right|\right)$$



#### where

- $\mu\,$  is the population mean under  ${\bf H}_0$
- $\overline{x}_0$  is the observed sample mean
- $\sigma\,$  is the population s.d.
- n is the sample size

## Modulus notation for two tail

 $\Pr(|\overline{X} - \mu| \ge a) \implies$  "the probability that the distance between  $\overline{\mu}$  and  $\mu$  is  $\ge a$ "

### Inverse normal

On CAS invNormCdf("L",  $\alpha$ ,  $\frac{\sigma}{n^{\alpha}}$ ,  $\mu$ )

### Errors

**Type I error**  $\mathbf{H}_0$  is rejected when it is **true** 

Type II error  $H_0$  is not rejected when it is false

	Actual result	
z-test	$\mathbf{H}_0$ true	$\mathbf{H}_0$ false
Reject $\mathbf{H}_0$	Type I error	Correct
Do not reject $\mathbf{H}_0$	Correct	Type II error