Year 12 Specialist

Andrew Lorimer

1 Complex numbers

 $\mathbb{C} = \{a + bi : a, b \in \mathbb{R}\}\$

Cartesian form: a + bi

Polar form: $r \operatorname{cis} \theta$

Properties

$$|z_1 z_2| = |z_1||z_2|$$

$$\left|\frac{z_1}{z_2}\right| = \frac{|z_1|}{|z_2|}$$

 $|z_1 + z_2| \le |z_1| + |z_2|$

Operations

	Cartesian	Polar	
$z_1 \pm z_2$	$(a \pm c)(b \pm d)i$	convert to $a + bi$	
$+k \times z$	ka + kbi	$kr \operatorname{cis} \theta$	
$-k \times z$	$\kappa a \pm \kappa o i$	$kr\operatorname{cis}(\theta\pm\pi)$	
$z_1 \cdot z_2$	ac - bd + (ad + bc)i	$r_1 r_2 \operatorname{cis}(\theta_1 + \theta_2)$	
$z_1 \div z_2$	$(z_1\overline{z_2}) \div z_2 ^2$	$\left(\frac{r_1}{r_2}\right)\operatorname{cis}(\theta_1-\theta_2)$	

Scalar multiplication in polar form

For $k \in \mathbb{R}^+$:

$$k(r\operatorname{cis}\theta) = kr\operatorname{cis}\theta$$

For $k \in \mathbb{R}^-$:

$$k(r\operatorname{cis}\theta) = kr\operatorname{cis}\left(\begin{cases} \theta - \pi & |0 < \operatorname{Arg}(z) \le \pi\\ \theta + \pi & |-\pi < \operatorname{Arg}(z) \le 0 \end{cases}\right)$$

Multiplicative inverse

$$z^{-1} = \frac{a - bi}{a^2 + b^2}$$
$$= \frac{\overline{z}}{|z|^2} a$$
$$= r \operatorname{cis}(-\theta)$$

Dividing over \mathbb{C}

$$\begin{aligned} \frac{z_1}{z_2} &= z_1 z_2^{-1} \\ &= \frac{z_1 \overline{z_2}}{|z_2|^2} \\ &= \frac{(a+bi)(c-di)}{c^2 + d^2} \end{aligned}$$

then rationalise denominator

Conjugate

conjg(a+bi)

$$\overline{z} = a \mp bi$$
$$= r\operatorname{cis}(-\theta)$$

/

Polar form

$$r \operatorname{cis} \theta = r \left(\cos \theta + i \sin \theta \right)$$

•
$$r = |z| = \sqrt{\text{Re}(z)^2 + \text{Im}(z)^2}$$

•
$$\theta = \arg(z)$$

• $Arg(z) \in (-\pi, \pi)$ (principal argument)

arg(a+bi)

• Multiple representations: $r \operatorname{cis} \theta = r \operatorname{cis} (\theta + 2n\pi) \text{ with } n \in \mathbb{Z} \text{ revolutions}$

•
$$\operatorname{cis} \pi = -1$$
, $\operatorname{cis} 0 = 1$

Properties

$$\overline{z_1 \pm z_2} = \overline{z_1} \pm \overline{z_2}$$

$$\overline{z_1 \cdot z_2} = \overline{z_1} \cdot \overline{z_2}$$

$$\overline{kz} = k\overline{z} \,\forall \, k \in \mathbb{R}$$

$$z\overline{z} = (a + bi)(a - bi)$$

$$= a^2 + b^2$$

$$= |z|^2$$

On CAS

 $\texttt{compToTrig(a+bi)} \iff \texttt{cExpand}\{\texttt{r} \cdot \texttt{cisX}\}$

Modulus

$$|z| = |\vec{Oz}| = \sqrt{a^2 + b^2}$$

de Moivres' theorem

 $(r\operatorname{cis}\theta)^n=r^n\operatorname{cis}(n\theta)$ where $n\in\mathbb{Z}$

Complex polynomials

$\underline{\text{Include}}$	\pm	for	all	solutio	ns,	incl.	ima	aginaı	у
				z^2 -	$+a^2$	=z	2 _	$(ai)^2$	

Sum of squares	= (z + ai)(z - ai)
Sum of cubes	$a^3 \pm b^3 = (a \pm b)(a^2 \mp ab + b^2)$

Division
$$P(z) = D(z)Q(z) + R(z)$$

Remainder Let
$$\alpha \in \mathbb{C}$$
. Remainder of

theorem
$$P(z) \div (z - \alpha)$$
 is $P(\alpha)$

Factor theorem
$$z - \alpha$$
 is a factor of $P(z) \iff$

$$P(\alpha) = 0 \text{ for } \alpha \in \mathbb{C}$$
Conjugate root $P(z) = 0 \text{ at } z = a \pm bi \ (\Longrightarrow)$

theorem both
$$z_1$$
 and $\overline{z_1}$ are solutions)

Factor theorem

If
$$\beta z + \alpha$$
 is a factor of $P(z)$,

then
$$P(-\frac{\alpha}{\beta}) = 0$$
.

nth roots

*n*th roots of $z = r \operatorname{cis} \theta$ are:

$$z = r^{\frac{1}{n}} \operatorname{cis}\left(\frac{\theta + 2k\pi}{n}\right)$$

- Same modulus for all solutions
- Arguments separated by $\frac{2\pi}{n}$: there are n roots
- If one square root is a + bi, the other is -a bi
- Give one implicit *n*th root z_1 , function is $z = z_1^n$
- Solutions of $z^n=a$ where $a\in\mathbb{C}$ lie on the circle $x^2+y^2=\left(|a|^{\frac{1}{n}}\right)^2$ (intervals of $\frac{2\pi}{n}$)

For $0 = az^2 + bz + c$, use quadratic formula:

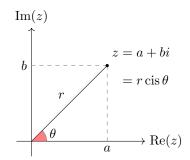
$$z = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Fundamental theorem of algebra

A polynomial of degree n can be factorised into n linear factors in \mathbb{C} :

$$\implies P(z) = a_n(z - \alpha_1)(z - \alpha_2)(z - \alpha_3) \dots (z - \alpha_n)$$
where $\alpha_1, \alpha_2, \alpha_3, \dots, \alpha_n \in \mathbb{C}$

Argand planes



- Multiplication by $i \implies \text{CCW rotation of } \frac{\pi}{2}$
- Addition: $z_1 + z_2 \equiv \overrightarrow{Oz_1} + \overrightarrow{Oz_2}$

Sketching complex graphs

Linear

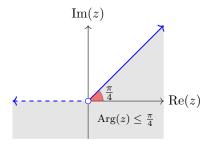
- $\operatorname{Re}(z) = c$ or $\operatorname{Im}(z) = c$ (perpendicular bisector)
- $\operatorname{Im}(z) = m \operatorname{Re}(z)$
- $|z+a| = |z+b| \implies 2(a-b)x = b^2 a^2$

Geometric: equidistant from a, b

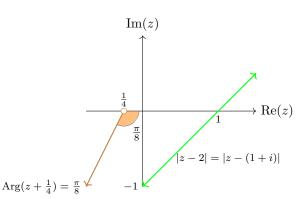
Circles

- $|z z_1|^2 = c^2 |z_2 + 2|^2$
- $|z (a + bi)| = c \implies (x a)^2 + (y b)^2 = c^2$

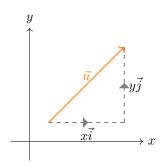
Loci $Arg(z) < \theta$



Rays $Arg(z - b) = \theta$



2 Vectors



Column notation

$$\begin{bmatrix} x \\ y \end{bmatrix} \iff x\mathbf{i} + y\mathbf{j}$$

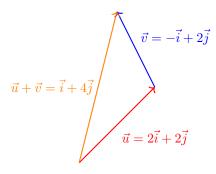
$$\begin{bmatrix} x_2 - x_1 \\ y_2 - y_1 \end{bmatrix}$$
 between $A(x_1, y_1), B(x_2, y_2)$

Scalar multiplication

$$k \cdot (x\mathbf{i} + y\mathbf{j}) = kx\mathbf{i} + ky\mathbf{j}$$

For $k \in \mathbb{R}^-$, direction is reversed

Vector addition



$$(x\mathbf{i} + y\mathbf{j}) \pm (a\mathbf{i} + b\mathbf{j}) = (x \pm a)\mathbf{i} + (y \pm b)\mathbf{j}$$

- Draw each vector head to tail then join lines
- Addition is commutative (parallelogram)

•
$$u - v = u + (-v) \implies \overrightarrow{AB} = b - a$$

Magnitude

$$|(x\boldsymbol{i} + y\boldsymbol{j})| = \sqrt{x^2 + y^2}$$

Parallel vectors

$$\boldsymbol{u}||\boldsymbol{v}\iff\boldsymbol{u}=k\boldsymbol{v} \text{ where } k\in\mathbb{R}\setminus\{0\}$$

For parallel vectors \boldsymbol{a} and \boldsymbol{b} :

$$m{a} \cdot m{b} = egin{cases} |m{a}| |m{b}| & ext{if same direction} \ -|m{a}| |m{b}| & ext{if opposite directions} \end{cases}$$

Perpendicular vectors

$$\mathbf{a} \perp \mathbf{b} \iff \mathbf{a} \cdot \mathbf{b} = 0 \quad \text{(since } \cos 90 = 0\text{)}$$

Unit vector $|\hat{a}| = 1$

$$\hat{a} = \frac{1}{|a|}a$$

$$= a \cdot |a|$$

Scalar product $a \cdot b$



$$\mathbf{a} \cdot \mathbf{b} = a_1 b_1 + a_2 b_2$$

= $|\mathbf{a}| |\mathbf{b}| \cos \theta$
($0 \le \theta \le \pi$) - from cosine rule

On CAS: dotP([a b c], [d e f])

Properties

1.
$$k(\boldsymbol{a} \cdot \boldsymbol{b}) = (k\boldsymbol{a}) \cdot \boldsymbol{b} = \boldsymbol{a} \cdot (k\boldsymbol{b})$$

2.
$$a \cdot 0 = 0$$

3.
$$a \cdot (b + c) = a \cdot b + a \cdot c$$

4.
$$\mathbf{i} \cdot \mathbf{i} = \mathbf{j} \cdot \mathbf{j} = \mathbf{k} \cdot \mathbf{k} = 1$$

5.
$$\mathbf{a} \cdot \mathbf{b} = 0 \implies \mathbf{a} \perp \mathbf{b}$$

6.
$$\mathbf{a} \cdot \mathbf{a} = |\mathbf{a}|^2 = a^2$$

Angle between vectors

$$\cos \theta = \frac{\boldsymbol{a} \cdot \boldsymbol{b}}{|\boldsymbol{a}||\boldsymbol{b}|} = \frac{a_1 b_1 + a_2 b_2}{|\boldsymbol{a}||\boldsymbol{b}|}$$

On CAS: angle([a b c], [a b c])

$$(Action \rightarrow Vector \rightarrow Angle)$$

Angle between vector and axis

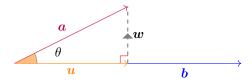
For $\mathbf{a} = a_1 \mathbf{i} + a_2 \mathbf{j} + a_3 \mathbf{k}$ which makes angles α, β, γ with positive side of x, y, z axes:

$$\cos \alpha = \frac{a_1}{|\boldsymbol{a}|}, \quad \cos \beta = \frac{a_2}{|\boldsymbol{a}|}, \quad \cos \gamma = \frac{a_3}{|\boldsymbol{a}|}$$

On CAS: angle([a b c], [1 0 0])

for angle between $a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$ and x-axis

Projections & resolutes



$\parallel b$ (vector projection/resolute)

$$egin{aligned} oldsymbol{u} &= rac{oldsymbol{a} \cdot oldsymbol{b}}{|oldsymbol{b}|^2} oldsymbol{b} \ &= \left(rac{oldsymbol{a} \cdot oldsymbol{b}}{|oldsymbol{b}|}
ight) \left(rac{oldsymbol{b}}{|oldsymbol{b}|}
ight) \ &= (oldsymbol{a} \cdot \hat{oldsymbol{b}}) \hat{oldsymbol{b}} \end{aligned}$$

$\perp b$ (perpendicular projection)

$$w = a - u$$

|u| (scalar projection/resolute)

$$s = |\mathbf{u}|$$

$$= \mathbf{a} \cdot \hat{\mathbf{b}}$$

$$= \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{b}|}$$

$$= |\mathbf{a}| \cos \theta$$

Rectangular (\parallel,\perp) components

$$a = rac{a \cdot b}{b \cdot b}b + \left(a - rac{a \cdot b}{b \cdot b}b
ight)$$

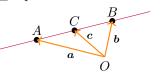
Vector proofs

Concurrent: intersection of ≥ 3 lines



Collinear points

 \geq 3 points lie on the same line



e.g. Prove that

$$\overrightarrow{AC} = m\overrightarrow{AB} \iff \mathbf{c} = (1 - m)\mathbf{a} + m\mathbf{b}$$

$$\implies \mathbf{c} = \overrightarrow{OA} + \overrightarrow{AC}$$

$$= \overrightarrow{OA} + m\overrightarrow{AB}$$

$$= \mathbf{a} + m(\mathbf{b} - \mathbf{a})$$

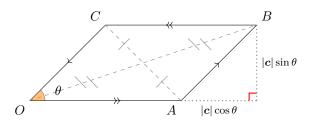
$$= \mathbf{a} + m\mathbf{b} - m\mathbf{a}$$

$$= (1 - m)\mathbf{a} + m\mathbf{b}$$

Also,
$$\Longrightarrow \overrightarrow{OC} = \lambda \overrightarrow{OA} + \mu \overrightarrow{OB}$$

where $\lambda + \mu = 1$
If C lies along \overrightarrow{AB} , $\Longrightarrow 0 < \mu < 1$

Parallelograms



- Diagonals \overrightarrow{OB} , \overrightarrow{AC} bisect each other
- If diagonals are equal length, it is a rectangle
- $\bullet \ |\overrightarrow{OB}|^2 + |\overrightarrow{CA}|^2 = |\overrightarrow{OA}|^2 + |\overrightarrow{AB}|^2 + |\overrightarrow{CB}|^2 + |\overrightarrow{OC}|^2$
- Area = $\mathbf{c} \cdot \mathbf{a}$

Useful vector properties

- $\boldsymbol{a} \parallel \boldsymbol{b} \implies \boldsymbol{b} = k\boldsymbol{a}$ for some $k \in \mathbb{R} \setminus \{0\}$
- ullet If a and b are parallel with at least one point in common, then they lie on the same straight line
- $\mathbf{a} \perp \mathbf{b} \iff \mathbf{a} \cdot \mathbf{b} = 0$
- $\bullet \ \boldsymbol{a} \cdot \boldsymbol{a} = |\boldsymbol{a}|^2$

Linear dependence

a, b, c are linearly dependent if they are $\not\parallel$ and:

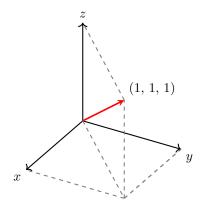
$$0 = k\mathbf{a} + l\mathbf{b} + m\mathbf{c}$$

$$\therefore \mathbf{c} = m\mathbf{a} + n\mathbf{b}$$
 (simultaneous)

a, b, and c are linearly independent if no vector in the set is expressible as a linear combination of other vectors in set, or if they are parallel.

Three-dimensional vectors

Right-hand rule for axes: z is up or out of page.



Parametric vectors

Parametric equation of line through point (x_0, y_0, z_0) and parallel to $a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$ is:

$$\begin{cases} x = x_o + a \cdot t \\ y = y_0 + b \cdot t \\ z = z_0 + c \cdot t \end{cases}$$

3 Circular functions

 $\sin(bx)$ or $\cos(bx)$: period = $\frac{2\pi}{b}$

 $\tan(nx)$: period = $\frac{\pi}{n}$

asymptotes at
$$x = \frac{(2k+1)\pi}{2n} \mid k \in \mathbb{Z}$$

Reciprocal functions

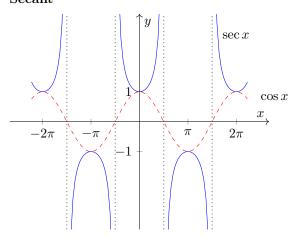
Cosecant

$$\csc \theta = \frac{1}{\sin \theta} \mid \sin \theta \neq 0$$

• Domain = $\mathbb{R} \setminus n\pi : n \in \mathbb{Z}$

- Range = $\mathbb{R} \setminus (-1, 1)$
- Turning points at $\theta = \frac{(2n+1)\pi}{2} \mid n \in \mathbb{Z}$
- Asymptotes at $\theta = n\pi \mid n \in \mathbb{Z}$

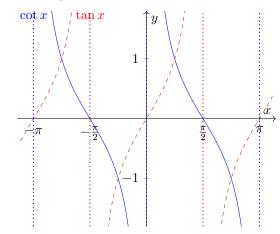
Secant



$$\sec \theta = \frac{1}{\cos \theta} \mid \cos \theta \neq 0$$

- Domain = $\mathbb{R} \setminus \frac{(2n+1)\pi}{2} : n \in \mathbb{Z}$
- Range = $\mathbb{R} \setminus (-1, 1)$
- Turning points at $\theta = n\pi \mid n \in \mathbb{Z}$
- Asymptotes at $\theta = \frac{(2n+1)\pi}{2} \mid n \in \mathbb{Z}$

Cotangent



$$\cot \theta = \frac{\cos \theta}{\sin \theta} \mid \sin \theta \neq 0$$

- Domain = $\mathbb{R} \setminus \{n\pi : n \in \mathbb{Z}\}$
- Range = \mathbb{R}
- Asymptotes at $\theta = n\pi \mid n \in \mathbb{Z}$

Symmetry properties

$$\sec(\pi \pm x) = -\sec x$$
$$\sec(-x) = \sec x$$
$$\csc(\pi \pm x) = \mp \csc x$$
$$\csc(-x) = -\csc x$$
$$\cot(\pi \pm x) = \pm \cot x$$
$$\cot(-x) = -\cot x$$

Complementary properties

$$\sec\left(\frac{\pi}{2} - x\right) = \csc x$$
$$\csc\left(\frac{\pi}{2} - x\right) = \sec x$$
$$\cot\left(\frac{\pi}{2} - x\right) = \tan x$$
$$\tan\left(\frac{\pi}{2} - x\right) = \cot x$$

Pythagorean identities

$$1 + \cot^2 x = \csc^2 x$$
, where $\sin x \neq 0$
 $1 + \tan^2 x = \sec^2 x$, where $\cos x \neq 0$

Compound angle formulas

$$\cos(x \pm y) = \cos x + \cos y \mp \sin x \sin y$$
$$\sin(x \pm y) = \sin x \cos y \pm \cos x \sin y$$
$$\tan(x \pm y) = \frac{\tan x \pm \tan y}{1 \mp \tan x \tan y}$$

Double angle formulas

$$\cos 2x = \cos^2 x - \sin^2 x$$

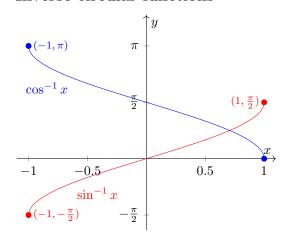
$$= 1 - 2\sin^2 x$$

$$= 2\cos^2 x - 1$$

$$\sin 2x = 2\sin x \cos x$$

$$\tan 2x = \frac{2\tan x}{1 - \tan^2 x}$$

Inverse circular functions

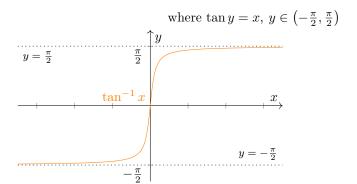


Inverse functions: $f(f^{-1}(x)) = x$ (restrict domain)

$$\sin^{-1}: [-1,1] \to \mathbb{R}, \quad \sin^{-1}x = y$$
 where $\sin y = x, \ y \in \left[\frac{-\pi}{2}, \frac{\pi}{2}\right]$

$$\cos^{-1}:[-1,1]\to\mathbb{R},\quad \cos^{-1}x=y$$
 where $\cos y=x,\;y\in[0,\pi]$

$$\tan^{-1}: \mathbb{R} \to \mathbb{R}, \quad \tan^{-1} x = y$$



Mensuration

Sectors:
$$A = \pi r^2 \frac{\theta}{2\pi}$$
$$= \frac{r^2 \theta}{2}$$

Segments:
$$A = \frac{r^2}{2} (\theta - \sin \theta)$$

Chords:
$$\operatorname{crd} \theta = \sqrt{(1 - \cos \theta)^2 + \sin^2 \theta}$$

= $\sqrt{2 - 2\cos \theta}$
= $2\sin\left(\frac{\theta}{2}\right)$

4 Differential calculus

$$f'(x) = \lim_{\delta x \to 0} \frac{\delta y}{\delta x} = \frac{dy}{dx}$$

Limits

$$\lim_{x \to a} f(x)$$

 $L^-, \quad L^+ \quad \text{ limit from below/above}$ $\lim_{x \to a} f(x) \quad \text{ limit of a point}$

For solving $x \to \infty$, put all x terms in denominators e.g.

$$\lim_{x \to \infty} \frac{2x+3}{x-2} = \frac{2+\frac{3}{x}}{1-\frac{2}{x}} = \frac{2}{1} = 2$$

Limit theorems

- 1. For constant function f(x) = k, $\lim_{x \to a} f(x) = k$
- 2. $\lim_{x\to a} (f(x) \pm g(x)) = F \pm G$
- 3. $\lim_{x\to a} (f(x) \times g(x)) = F \times G$
- 4. $\therefore \lim_{x\to a} c \times f(x) = cF$ where c = constant
- 5. $\lim_{x\to a} \frac{f(x)}{g(x)} = \frac{F}{G}, G \neq 0$
- 6. f(x) is continuous $\iff L^- = L^+ = f(x) \, \forall x$

Gradients

Secant (chord) - line joining two points on curveTangent - line that intersects curve at one point

Points of Inflection

Stationary point - i.e. f'(x) = 0Point of inflection - max |gradient| (i.e. f'' = 0)

Strictly increasing/decreasing

For x_2 and x_1 where $x_2 > x_1$:

strictly increasing

where
$$f(x_2) > f(x_1)$$
 or $f'(x) > 0$

strictly decreasing

where
$$f(x_2) < f(x_1)$$
 or $f'(x) < 0$

Endpoints are included, even where $\frac{dy}{dx}=0$

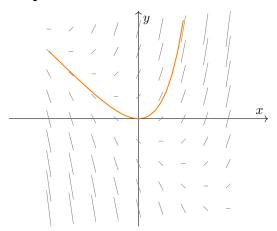
Second derivative

$$f(x) \longrightarrow f'(x) \longrightarrow f''(x)$$

$$\implies y \longrightarrow \frac{dy}{dx} \longrightarrow \frac{d^2y}{dx^2}$$

Order of polynomial nth derivative decrements each time the derivative is taken

Slope fields



- f'(a) = 0, f''(a) > 0local min at (a, f(a)) (concave up)
- f'(a) = 0, f''(a) < 0local max at (a, f(a)) (concave down)
- f''(a) = 0point of inflection at (a, f(a))
- f''(a) = 0, f'(a) = 0stationary point of inflection at (a, f(a))

	$\frac{d^2y}{dx^2} > 0$	$\frac{d^2y}{dx^2} < 0$	$\frac{d^2y}{dx^2} = 0 \text{ (inflection)}$
$\frac{dy}{dx} > 0$			
	Rising (concave up)	Rising (concave down)	Rising inflection point
$\frac{dy}{dx} < 0$	Falling (concave up)	Falling (concave down)	Falling inflection point
	rannig (concave up)	raining (concave down)	raning innection point
$\frac{dy}{dx} = 0$			
	Local minimum	Local maximum	Stationary inflection point

Implicit Differentiation

Used for differentiating circles etc.

If p and q are expressions in x and y such that p=q, for all x and y, then:

$$\frac{dp}{dx} = \frac{dq}{dx}$$
 and $\frac{dp}{dy} = \frac{dq}{dy}$

On CAS

 $Action \rightarrow Calculation$

 $impDiff(y^2+ax=5, x, y)$

Function of the dependent variable

If $\frac{dy}{dx} = g(y)$, then $\frac{dx}{dy} = 1 \div \frac{dy}{dx} = \frac{1}{g(y)}$. Integrate both sides to solve equation. Only add c on one side. Express e^c as A.

Reciprocal derivatives

$$\frac{1}{\frac{dy}{dy}} = \frac{dx}{dy}$$

Differentiating x = f(y)

Find
$$\frac{dx}{dy}$$
, then $\frac{dy}{dx} = \frac{1}{\left(\frac{dx}{dy}\right)}$

Parametric equations

$$\frac{dy}{dt} = \frac{dy}{dx} \cdot \frac{dx}{dt}$$

$$\therefore \frac{dy}{dx} = \frac{\left(\frac{dy}{dt}\right)}{\left(\frac{dx}{dt}\right)} \text{ provided } \frac{dx}{dt} \neq 0$$

$$\frac{d^2y}{dx^2} = \frac{\left(\frac{dy'}{dt}\right)}{\left(\frac{dx}{dt}\right)} \text{ where } y' = \frac{dy}{dx}$$

Integration

$$\int f(x) \cdot dx = F(x) + c \quad \text{where } F'(x) = f(x)$$

Properties

$$\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx$$
$$\int_a^a f(x) dx = 0$$
$$\int_a^b k \cdot f(x) dx = k \int_a^b f(x) dx$$
$$\int_a^b f(x) \pm g(x) dx = \int_a^b f(x) dx \pm \int_a^b g(x) dx$$
$$\int_a^b f(x) dx = -\int_b^a f(x) dx$$

Integration by substitution

$$\int f(u)\frac{du}{dx} \cdot dx = \int f(u) \cdot du$$

f(u) must be 1:1 \implies one x for each y

e.g. for
$$y = \int (2x+1)\sqrt{x+4} \cdot dx$$

let $u = x+4$
 $\Rightarrow \frac{du}{dx} = 1$
 $\Rightarrow x = u-4$
then $y = \int (2(u-4)+1)u^{\frac{1}{2}} \cdot du$
(solve as normal integral)

Definite integrals by substitution

For $\int_a^b f(x) \frac{du}{dx} \cdot dx$, evaluate new a and b for $f(u) \cdot du$.

Trigonometric integration

$$\sin^m x \cos^n x \cdot dx$$

m is odd: m = 2k + 1 where $k \in \mathbb{Z}$ $\implies \sin^{2k+1} x = (\sin^2 z)^k \sin x = (1 - \cos^2 x)^k \sin x$ Substitute $u = \cos x$

n is odd: n = 2k + 1 where $k \in \mathbb{Z}$ $\implies \cos^{2k+1} x = (\cos^2 x)^k \cos x = (1 - \sin^2 x)^k \cos x$ Substitute $u = \sin x$

m and n are even: use identities...

- $\bullet \sin^2 x = \frac{1}{2}(1 \cos 2x)$
- $\cos^2 x = \frac{1}{2}(1 + \cos 2x)$
- $\sin 2x = 2\sin x \cos x$

Separation of variables

If $\frac{dy}{dx} = f(x)g(y)$, then:

$$\int f(x) \, dx = \int \frac{1}{g(y)} \, dy$$

Partial fractions

To factorise $f(x) = \frac{\delta}{\alpha \cdot \beta}$:

$$\frac{\delta}{\alpha \cdot \beta \cdot \gamma} = \frac{A}{\alpha} + \frac{B}{\beta} + \frac{C}{\gamma} \tag{1}$$

Multiply by $(\alpha \cdot \beta \cdot \gamma)$:

$$\delta = \beta \gamma A + \alpha \gamma B + \alpha \beta C \tag{2}$$

Substitute $x = \{\alpha, \beta, \gamma\}$ into (2) to find denominators

Repeated linear factors

$$\frac{p(x)}{(x-a)^n} = \frac{A_1}{(x-a)} + \frac{A_2}{(x-a)^2} + \dots + \frac{A_n}{(x-a)^n}$$

Irreducible quadratic factors

e.g.
$$\frac{3x-4}{(2x-3)(x^2+5)} = \frac{A}{2x-3} + \frac{Bx+C}{x^2+5}$$

On CAS

Action \rightarrow Transformation:

To reverse, use combine(...)

Integrating
$$\frac{dy}{dx} = g(y)$$

if $\frac{dy}{dx} = g(y)$, then $x = \int \frac{1}{g(y)} dy$

Graphing integrals on CAS

On CAS

In main: Interactive \to Calculation $\to \int$ For restrictions, Define $f(x) = \dots$ then $f(x) | x > \dots$

Solids of revolution

Approximate as sum of infinitesimally-thick cylinders

Rotation about x-axis

$$V = \pi \int_{x=a}^{x=b} f(x)^2 dx$$

Rotation about y-axis

$$V = \pi \int_{y=a}^{y=b} x^2 dy$$
$$= \pi \int_{y=a}^{y=b} (f(y))^2 dy$$

Regions not bound by y = 0

$$V = \pi \int_{a}^{b} f(x)^{2} - g(x)^{2} dx$$
 where $f(x) > g(x)$

Length of a curve

For length of f(x) from $x = a \rightarrow x = b$:

Cartesian
$$L = \int_{a}^{b} \sqrt{1 + \left(\frac{dy}{dx}\right)^{2}} dx$$
 Parametric
$$L = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$

On CAS

- a) Evaluate formula
- b) Interactive \rightarrow Calculation \rightarrow Line \rightarrow arcLen

Applications of antidifferentiation

- x-intercepts of y = f(x) identify x-coordinates of stationary points on y = F(x)
- nature of stationary points is determined by sign of y = f(x) on either side of its x-intercepts
- if f(x) is a polynomial of degree n, then F(x) has degree n+1

To find stationary points of a function, substitute x value of given point into derivative. Solve for $\frac{dy}{dx} = 0$. Integrate to find original function.

Rates

Gradient at a point on parametric curve

$$\frac{dy}{dx} = \frac{dy}{dt} \div \frac{dx}{dt} \mid \frac{dx}{dt} \neq 0$$
 (chain rule)

$$\frac{d^2}{dx^2} = \frac{d(y')}{dx} = \frac{dy'}{dt} \div \frac{dx}{dt} \mid y' = \frac{dy}{dx}$$

Rational functions

$$f(x) = \frac{P(x)}{Q(x)}$$
 where P, Q are polynomial functions

Fundamental theorem of calculus

If f is continuous on [a, b], then

$$\int_{a}^{b} f(x) dx = F(b) - F(a)$$
 where $F = \int f dx$

Differential equations

Order - highest power inside derivative

Degree - highest power of highest derivative

e.g.
$$\left(\frac{dy^2}{d^2}x\right)^3$$
 order 2, degree 3

To verify solutions, find $\frac{dy}{dx}$ from y and substitute into original

Mixing problems

$$\left(\frac{dm}{dt}\right)_{\Sigma} = \left(\frac{dm}{dt}\right)_{\rm in} - \left(\frac{dm}{dt}_{\rm out}\right)$$

Euler's method

$$\frac{f(x+h) - f(x)}{h} \approx f'(x)$$
 for small h

$$\implies f(x+h) \approx f(x) + hf'(x)$$

If
$$\frac{dy}{dx} = g(x)$$
 with $x_0 = a$ and $y_0 = b$, then:

$$x_{n+1} = x_n + h$$

$$y_{n+1} = y_n + hg(x_n)$$

Derivatives

$$f(x) = f'(x)$$

$$\sin x \quad \cos x$$

$$\sin ax \quad a\cos ax$$

$$\cos x - \sin x$$

$$\cos ax - a\sin ax$$

$$\tan f(x)$$
 $f^2(x) \sec^2 f(x)$

$$e^x$$
 e^x

$$e^{ax}$$
 ae^{ax}

$$ax^{nx}$$
 $an \cdot e^{nx}$

$$\log_e x = \frac{1}{x}$$

$$\log_e ax \quad \frac{1}{x}$$

$$\log_e f(x) = \frac{f'(x)}{f(x)}$$

$$\sin(f(x)) \quad f'(x) \cdot \cos(f(x))$$

$$\sin^{-1} x = \frac{1}{\sqrt{1 - m^2}}$$

$$\sin^{-1} x$$
 $\frac{1}{\sqrt{1-x^2}}$
 $\cos^{-1} x$ $\frac{-1}{\sqrt{1-x^2}}$
 $\tan^{-1} x$ $\frac{1}{1+x^2}$

$$\tan^{-1} x \quad \frac{1}{1+x^2}$$

$$\frac{d}{dy}f(y) = \frac{1}{\frac{dx}{dy}}$$

(reciprocal)

$$uv \quad u\frac{dv}{dx} + v\frac{du}{dx}$$
 (product rule)

$$\frac{u}{v} \quad \frac{v\frac{du}{dx} - u\frac{dv}{dx}}{v^2} \qquad \text{(quotient rule)}$$

$$f(g(x))$$
 $f'(g(x)) \cdot g'(x)$

Antiderivatives

$$f(x) \int f(x) \cdot dx$$

$$k \text{ (constant)} \quad kx + c$$

$$x^n$$
 $\frac{1}{n+1}x^{n+1}$

$$ax^{-n}$$
 $a \cdot \log_e |x| + c$

$$\frac{1}{ax+b} \quad \frac{1}{a}\log_e(ax+b) + c$$

$$(ax + b)^{n} \frac{1}{a(n+1)}(ax + b)^{n-1} + c \mid n \neq 1$$

$$(ax + b)^{-1} \frac{1}{a}\log_{e}|ax + b| + c$$

$$e^{kx} \frac{1}{k}e^{kx} + c$$

$$(ax+b)^{-1}$$
 $\frac{1}{a}\log_e|ax+b|+c$

$$e^{kx}$$
 $\frac{1}{k}e^{kx} + c$

$$e^k e^k x + c$$

$$\sin kx \quad \frac{-1}{k}\cos(kx) + c$$

$$\cos kx = \frac{1}{k}\sin(kx) + c$$

$$\sec^2 kx \quad \frac{1}{k}\tan(kx) + c$$

$$\frac{1}{\sqrt{a^2 - x^2}} \quad \sin^{-1} \frac{x}{a} + c \mid a > 0$$

$$\sin kx \qquad \frac{1}{k}\cos(kx) + c$$

$$\cos kx \qquad \frac{1}{k}\sin(kx) + c$$

$$\sec^2 kx \qquad \frac{1}{k}\tan(kx) + c$$

$$\frac{1}{\sqrt{a^2 - x^2}} \qquad \sin^{-1}\frac{x}{a} + c \mid a > 0$$

$$\frac{-1}{\sqrt{a^2 - x^2}} \qquad \cos^{-1}\frac{x}{a} + c \mid a > 0$$

$$\frac{a}{a^2 - x^2} \quad \tan^{-1} \frac{x}{a} + c$$

$$\frac{f'(x)}{f(x)}$$
 $\log_e f(x) + c$

$$\int f(u) \cdot \frac{du}{dx} \cdot dx \quad \int f(u) \cdot du \qquad \text{(substitution)}$$

$$f(x) \cdot g(x) \quad \int [f'(x) \cdot g(x)] dx + \int [g'(x)f(x)] dx$$

Note
$$\sin^{-1}\left(\frac{x}{a}\right) + \cos^{-1}\left(\frac{x}{a}\right)$$
 is constant $\forall x \in (-a, a)$

Index identities

$$b^{m+n} = b^m \cdot b^n$$

$$(b^m)^n = b^{m \cdot n}$$

$$(b \cdot c)^n = b^n \cdot c^n$$

$$a^m \div a^n = a^{m-n}$$

Logarithmic identities

$$\log_b(xy) = \log_b x + \log_b y$$

$$\log_b\left(\frac{x}{y}\right) = \log_b(x) - \log_b(y)$$

$$\log_b x^n = n \log_b x$$

$$\log_b y^{x^n} = x^n \log_b y$$

5 Kinematics & Mechanics

Constant acceleration

- Position relative to origin
- Displacement relative to starting point

Velocity-time graphs

Displacement: signed area

Distance travelled: total area

acceleration =
$$\frac{d^2x}{dt^2} = \frac{dv}{dt} = v\frac{dv}{dx} = \frac{d}{dx}\left(\frac{1}{2}v^2\right)$$

	no
v = u + at	x
$v^2 = u^2 + 2as$	t
$s = \frac{1}{2}(v+u)t$	a
$s = ut + \frac{1}{2}at^2$	v
$s = vt - \frac{1}{2}at^2$	u

$$v_{\rm avg} = \frac{\Delta \rm position}{\Delta t}$$

speed = |velocity|
=
$$\sqrt{v_x^2 + v_y^2 + v_z^2}$$

Distance travelled between $t = a \rightarrow t = b$:

$$= \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$
 (2D)
$$= \int_{t=a}^{t=b} \frac{dx}{dt} dt$$
 (linear)

Shortest distance between $r(t_0)$ and $r(t_1)$:

$$= |\boldsymbol{r}(t_1) - \boldsymbol{r}(t_2)|$$

Vector functions

$$r(t) = xi + yj + zk$$

- If $r(t) \equiv$ position with time, then the graph of endpoints of $r(t) \equiv$ Cartesian path
- Domain of r(t) is the range of x(t)
- Range of r(t) is the range of y(t)

Vector calculus

Derivative

Let $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)(\mathbf{j})$. If both x(t) and y(t) are differentiable, then:

$$\boldsymbol{r}(t) = x(t)\boldsymbol{i} + y(t)\boldsymbol{j}$$

6 Dynamics

Resolution of forces

Resultant force is sum of force vectors

In angle-magnitude form

Cosine rule:
$$c^{2} = a^{2} + b^{2} - 2ab\cos\theta$$

Sine rule:
$$\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}$$

In i-j form

Vector of a N at θ to x axis is equal to $a \cos \theta \mathbf{i} + a \sin \theta \mathbf{j}$. Convert all force vectors then add.

To find angle of an $a\boldsymbol{i}+b\boldsymbol{j}$ vector, use $\theta=\tan^{-1}\frac{b}{a}$

Resolving in a given direction

The resolved part of a force P at angle θ is has magnitude $P\cos\theta$

To convert force $||\vec{OA}|$ to angle-magnitude form, find component $\perp \vec{OA}$ then:

$$|\mathbf{r}| = \sqrt{\left(||\vec{OA}|^2 + \left(\perp \vec{OA}\right)^2\right)}$$
$$\theta = \tan^{-1} \frac{\perp \vec{OA}}{||\vec{OA}|}$$

Newton's laws

- 1. Velocity is constant without ΣF
- 2. $\frac{d}{dt}\rho \propto \Sigma F \implies \mathbf{F} = m\mathbf{a}$
- 3. Equal and opposite forces

Weight

A mass of m kg has force of mg acting on it

Momentum ρ

 $\rho = mv$ (units kg m/s or Ns)

Reaction force R

- With no vertical velocity, R = mg
- With vertical acceleration, |R| = m|a| mg
- With force F at angle θ , then $R = mg F \sin \theta$

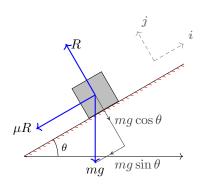
Friction

 $F_R = \mu R$ (friction coefficient)

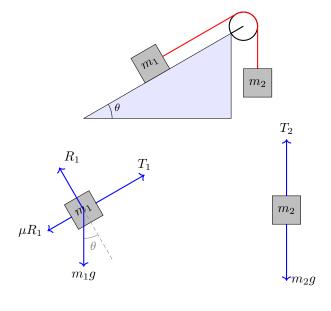
Inclined planes

$$F = |F| \cos \theta i + |F| \sin \theta j$$

- \bullet Normal force R is at right angles to plane
- ullet Let direction up the plane be i and perpendicular to plane j



Connected particles



• Suspended pulley: $T_1 = T_2$ $|a| = g \frac{m_1 - m_2}{m_1 + m_2} \text{ where } m_1 \text{ accelerates down}$

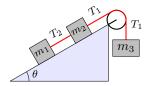
$$\left\{ \begin{array}{l} m_1g - T = m_1a \\ T - m_2g = m_2a \end{array} \right\} \implies m_1g - m_2g = m_1a + m_2a$$

• String pulling mass on inclined pane: Resolve parallel to plane

$$T - mg\sin\theta = ma$$

- Linear connection: find acceleration of system first
- Pulley on right angle: $a = \frac{m_2 g}{m_1 + m_2}$ where m_2 is suspended (frictionless on both surfaces)
- Pulley on edge of incline: find downwards force W_2 and components of mass on plane

In this example, note $T_1 \neq T_2$:



Equilibrium

$$\frac{A}{\sin a} = \frac{B}{\sin b} = \frac{C}{\sin c}$$
 (Lami's theorem)
$$c^2 = a^2 + b^2 - 2ab\cos\theta$$
 (cosine rule)

Three methods:

- 1. Lami's theorem (sine rule)
- 2. Triangle of forces (cosine rule)
- 3. Resolution of forces ($\Sigma F = 0$ simultaneous)

On CAS

To verify: Geometry tab, then select points with normal cursor. Click right arrow at end of toolbar and input point, then lock known constants.

Variable forces (DEs)

$$a = \frac{d^2x}{dt^2} = \frac{dv}{dt} = v\frac{dv}{dx} = \frac{d}{dx}\left(\frac{1}{2}v^2\right)$$

7 Statistics

Continuous random variables

A continuous random variable X has a pdf f such that:

1.
$$f(x) \ge 0 \forall x$$

$$2. \int_{-\infty}^{\infty} f(x) dx = 1$$

$$E(X) = \int_{\mathbf{X}} (x \cdot f(x)) dx$$
$$Var(X) = E \left[(X - \mu)^2 \right]$$

$$\Pr(X \le c) = \int_{-\infty}^{c} f(x) \, dx$$

Two random variables X, Y

If X and Y are independent:

$$E(aX + bY) = a E(X) + b E(Y)$$
$$Var(aX \pm bY \pm c) = a^{2} Var(X) + b^{2} Var(Y)$$

Linear functions $X \to aX + b$

$$\Pr(Y \le y) = \Pr(aX + b \le y)$$
$$= \Pr\left(X \le \frac{y - b}{a}\right)$$
$$= \int_{-a}^{\frac{y - b}{a}} f(x) dx$$

Mean: E(aX + b) = a E(X) + bVariance: $Var(aX + b) = a^2 Var(X)$

Expectation theorems

For some non-linear function g, the expected value E(g(X)) is not equal to g(E(X)).

$$E(X^2) = \text{Var}(X) - [E(X)]^2$$

 $E(X^n) = \Sigma x^n \cdot p(x)$ (non-linear)
 $\neq [E(X)]^n$

$$E(aX \pm b) = aE(X) \pm b$$
 (linear)

$$E(b) = b (\forall b \in \mathbb{R})$$

$$E(X + Y) = E(X) + E(Y)$$
 (two variables)

Sample mean

Approximation of the **population mean** determined experimentally.

$$\overline{x} = \frac{\sum x}{n}$$

where

n is the size of the sample (number of sample points) x is the value of a sample point

On CAS

- 1. Spreadsheet
- 2. In cell A1:

 mean(randNorm(sd, mean, sample size))
- 3. Edit \rightarrow Fill \rightarrow Fill Range
- 4. Input range as A1:An where n is the number of samples
- 5. Graph \rightarrow Histogram

Sample size of n

$$\overline{X} = \sum_{i=1}^{n} \frac{x_i}{n} = \frac{\sum x}{n}$$

Sample mean is distributed with mean μ and sd $\frac{\sigma}{\sqrt{n}}$ (approaches these values for increasing sample size n).

For a new distribution with mean of n trials, $\mathrm{E}(X') = \mathrm{E}(X)$, $\mathrm{sd}(X') = \frac{\mathrm{sd}(X)}{\sqrt{n}}$

On CAS

Spreadsheet \rightarrow Catalog

randNorm(sd, mean, n)

where ${\tt n}$ is the number of samples. Show histogram with Histogram key in top left.

To calculate parameters of a dataset:

 $Calc \rightarrow One-variable$

 \overline{x} is the sample mean

 σ is the population sd

n is the sample size from which \overline{x} was calculated

On CAS

 $Menu \rightarrow Stats \rightarrow Calc \rightarrow Interval$

Set $Type = One\text{-}Sample\ Z\ Int$

and select Variable

Normal distributions

$$Z = \frac{X - \mu}{\sigma}$$

Normal distributions must have area (total prob.) of 1 $\implies \int_{-\infty}^{\infty} f(x) dx = 1$

mean = mode = median

Always express z as +ve. Express confidence interval as ordered pair.

Central limit theorem

If X is randomly distributed with mean μ and sd σ , then with an adequate sample size n the distribution of the sample mean \overline{X} is approximately normal with mean $E(\overline{X})$ and $\operatorname{sd}(\overline{X}) = \frac{\sigma}{\sqrt{n}}$.

Confidence intervals

- Point estimate: single-valued estimate of the population mean from the value of the sample mean \overline{x}
- Interval estimate: confidence interval for population mean μ
- C% confidence interval $\implies C\%$ of samples will contain population mean μ

95% confidence interval

For 95% c.i. of population mean μ :

$$x \in \left(\overline{x} \pm 1.96 \frac{\sigma}{\sqrt{n}}\right)$$

where:

Margin of error

For 95% confidence interval of μ :

$$M = 1.96 \times \frac{\sigma}{\sqrt{n}}$$

$$\implies n = \left(\frac{1.96\sigma}{M}\right)^2$$

Always round n up to a whole number of samples.

General case

For C% c.i. of population mean μ :

$$x \in \left(\overline{x} \pm k \frac{\sigma}{\sqrt{n}}\right)$$

where k is such that $Pr(-k < Z < k) = \frac{C}{100}$

Confidence interval for multiple trials

For a set of n confidence intervals (samples), there is 0.95^n chance that all n intervals contain the population mean μ .

8 Hypothesis testing

Note hypotheses are always expressed in terms of population parameters

Null hypothesis H₀

Sample drawn from population has same mean as control population, and any difference can be explained by sample variations.

Alternative hypothesis H₁

Amount of variation from control is significant, despite standard sample variations.

p-value

Probability of observing a value of the sample statistic as significant as the one observed, assuming null hypothesis is true.

For one-tail tests:

$$p\text{-value} = \Pr\left(\overline{X} \leq \mu(\mathbf{H}_1) \mid \mu = \mu(\mathbf{H}_0)\right)$$
$$= \Pr\left(Z \leq \frac{(\mu(\mathbf{H}_1) - \mu(\mathbf{H}_0)) \cdot \sqrt{n}}{\operatorname{sd}(X)}\right)$$

then use normCdf with std. norm.

p	Conclusion
> 0.05	insufficient evidence against \mathbf{H}_0
< 0.05 (5%)	good evidence against \mathbf{H}_0
< 0.01 (1%)	strong evidence against \mathbf{H}_0
< 0.001 (0.1%)	very strong evidence against \mathbf{H}_0

Finding n for a given p-value

Find c such that $Pr(Z \leq c)$ such that $c = \alpha$ (use invNormCdf on CAS).

Significance level α

The condition for rejecting the null hypothesis.

If $p < \alpha$, null hypothesis is **rejected** If $p > \alpha$, null hypothesis is **accepted**

z-test

Hypothesis test for a mean of a sample drawn from a normally distributed population with a known standard deviation.

On CAS

 $Menu \rightarrow Statistics \rightarrow Calc \rightarrow Test.$

Select One-Sample Z-Test and Variable, then input:

 μ cond: same operator as \mathbf{H}_1

expected sample mean (null hypoth- μ_0 :

esis)

standard deviation (null hypothesis) σ :

sample mean \overline{x} : n: sample size

One-tail and two-tail tests

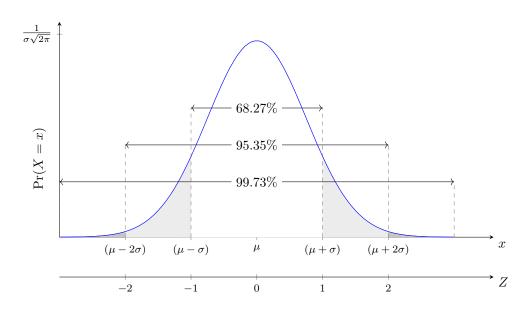
$$p$$
-value (two-tail) = $2 \times p$ -value (one-tail)

One tail

- μ has changed in one direction
- State " $\mathbf{H}_1: \mu \leq \text{known population mean}$ "

Two tail

• Direction of $\Delta \mu$ is ambiguous



• State " $\mathbf{H}_1: \mu \neq \text{known population mean}$ "

$$p\text{-value} = \Pr(|\overline{X} - \mu| \ge |\overline{x}_0 - \mu|)$$
$$= \left(|Z| \ge \left| \frac{\overline{x}_0 - \mu}{\sigma \div \sqrt{n}} \right| \right)$$

where

 μ is the population mean under \mathbf{H}_0

 \overline{x}_0 is the observed sample mean

 σ is the population s.d.

n is the sample size

Modulus notation for two tail

 $\Pr(|\overline{X} - \mu| \ge a) \implies$ "the probability that the distance between $\overline{\mu}$ and μ is $\ge a$ "

Inverse normal

Errors

Type I error H_0 is rejected when it is true

Type II error H_0 is not rejected when it is false

	Actual result		
z-test	\mathbf{H}_0 true	\mathbf{H}_0 false	
Reject \mathbf{H}_0	Type I error	Correct	
Do not reject \mathbf{H}_0	Correct	Type II error	